

EN1-06: Simple Robotics

October 7th, 2016

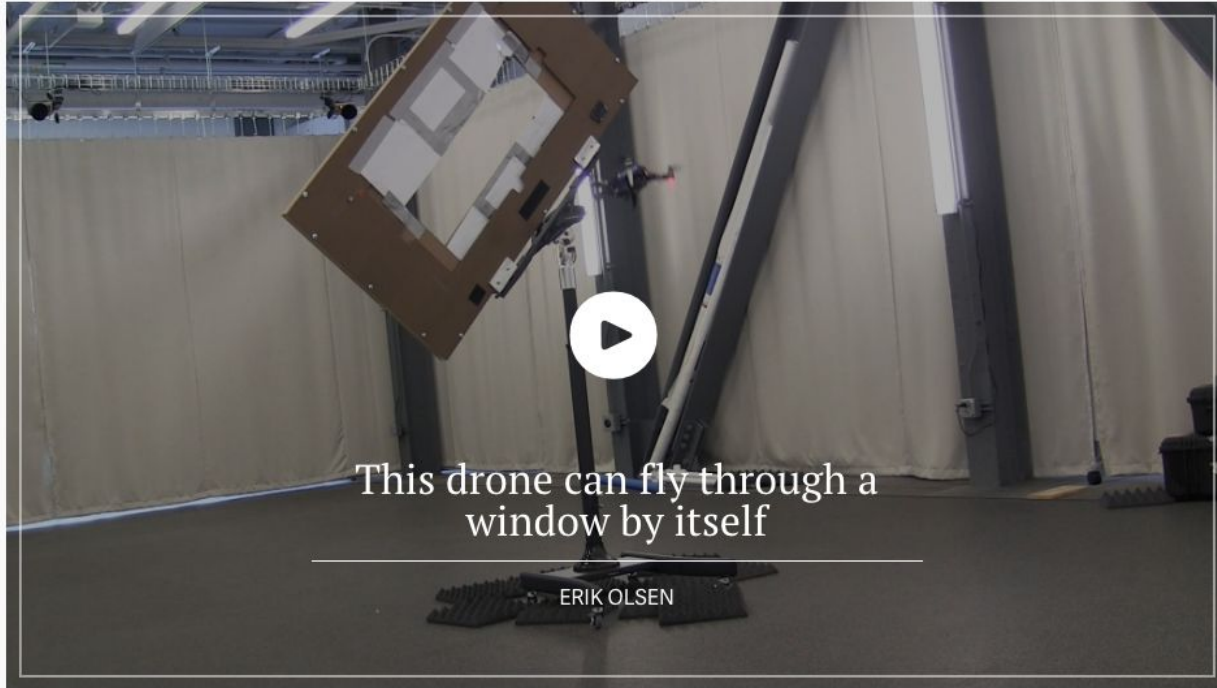


Schedule

- In the News
- Recruiting Mechanical Help
- Assignment 4: Robotic Magic Trick
- Hands-on Activity: Sound, Clusters, and Drawing

In the News

This little drone can zip through a window on its own



<http://qz.com/787937/scientists-have-built-an-autonomous-drone-that-can-figure-out-how-to-fly-through-windows-without-a-human-pilot/>

Assignment 4: Robotic Magic Trick

Project 4: Robotic Magic Trick

EN1-06 Fall 2016

Project (in-class demonstration/video presentation) due on Monday, October 17th, 2016

Documentation (description, images, videos, code, etc) due to website by Mon (10/17) by 9pm

Project Description: Create a robotic magic trick (either performed by the robot or performed by you and facilitated by the robot).

Hardware and Programming: You will use your LEGO MINDSTORMS EV3 Kit as well as any other materials needed for achieving the effect. You will program your robot in LabVIEW.

Assignment: You can work in pairs or groups of four (your choice); the complexity of the robot/project should reflect the size of your group (and this being a “two week” long project). For this assignment the goal is to perform a magic trick leveraging the LEGO MINDSTORMS EV3, either having the robot perform the magic trick (e.g. autonomously) or having you (the human) perform the magic trick facilitated by some robotic mechanism. The trick only needs to work once, and from a particular angle (you will be submitting a video recording of the trick; it does *not* need to be performed live). In addition to the video of the trick being performed, you need to submit a second video documenting/demonstrating the mechanism (yes, revealing the “trick,” which of course a true magician would never do!).

How Do I...?

Challenge 1: Drive the Motor forward 5 seconds and back 5 seconds

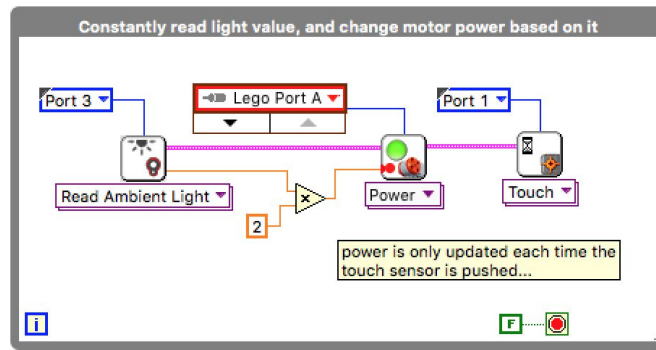
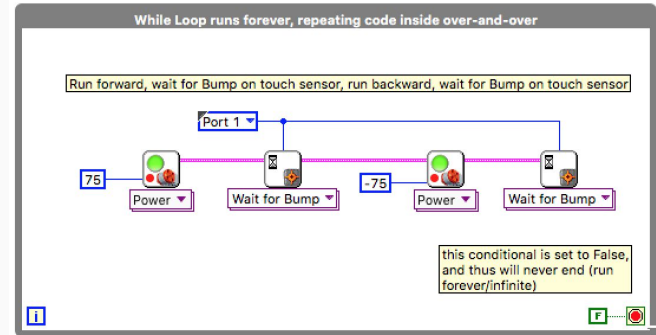
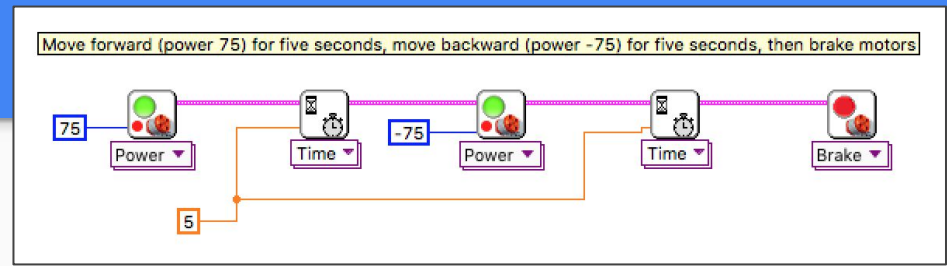
Challenge 2: Use Touch Sensor to “toggle” direction of the motor

Challenge 3: The motor moves as fast as the light sensor reads

Challenge 4: Display sensor value on the EV3 Screen

Challenge 5: Display sensor value on the LabVIEW Front Panel (value? meter? graph?)

Challenge 6: Save collection of sensor data values (e.g. light value each time you click touch sensor) and export to file for analysis in Excel



Three ideas today: Notes, Clusters, Drawing

Ability to play tones (440 Hz default)

Also:

- Piano: play red, green, blue songs
- Play Sound File (.rso)
- Play Note (A,B,C...)



Tone [Tone.vi]

Tone (440 Hz) ————

NXT/EV3 ————

Duration (500 ms) ————

————— NXT/EV3

Plays the specified tone on the NXT/EV3 brick for the specified duration (ms).

Inputs

NXT/EV3 connects to NXT/EV3 terminal of previous VI to establish the flow of the program.

Tone (440 Hz) is the Tone (Hz) to play. Minimum tone on the NXT/EV3 is around 50 Hz And Max is around 7000Hz. Default tone is 440Hz.

Duration (500 ms) is the length of time to play the song in ms. Default is 500ms.

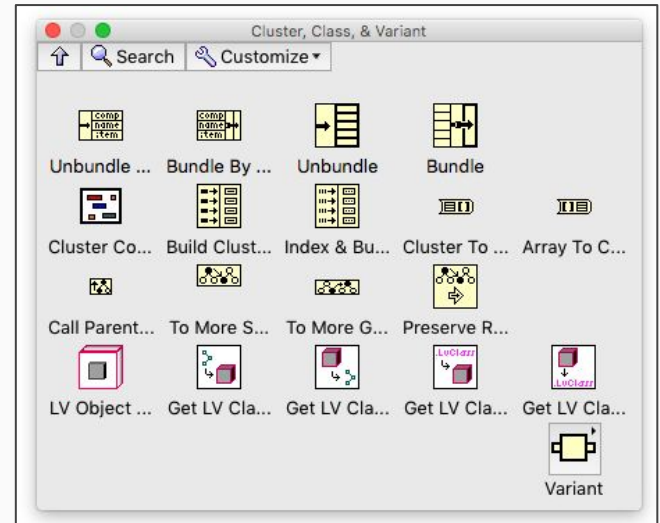
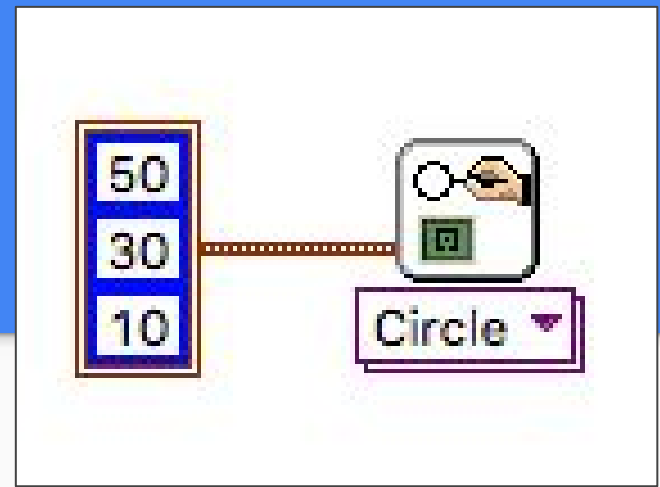
Outputs

NXT/EV3 wires to NXT/EV3 terminal of next VI to establish the flow of the program.

Clusters

“Bundle” Multiple Pieces of Data Together into a Cluster

- Bundle
- Unbundle



Challenges

Sound Challenges:

Challenge 1: Play Notes and Tones

Challenge 2a: Change Tone based on Light Value; scale value?

Challenge 3b: Change Tone based on Motor Value; deal with negative values?

Drawing Challenges:

Challenge 1: Draw a circle and square on the screen

Challenge 2: Move the circle based on the loop counter. Slow down loop? Keep circle on the screen?

Challenge 3: Move circle based on motor input(s). Etch-a-sketch?